

EM27/SUN activities at Heidelberg – mobile deployments on ships and vans

Institute of Environmental Physics, Heidelberg University

André Butz, Ralph Kleinschek, Marvin Knapp,
Benedikt Hemmer, Valentin Hanft, Ken von Büнау ...

+ many student contributors

+ close collaboration with KIT, NIES, TUM and other institutes for field
campaigns



Klappenbach, <https://doi.org/10.5194/amt-8-5023-2015>, AMT, 2015;
Butz et al., <https://doi.org/10.5194/amt-10-1-2017>, AMT, 2017;
Luther et al., <https://doi.org/10.5194/amt-12-5217-2019>, AMT, 2019;
Knapp et al., <https://doi.org/10.5194/essd-2020-132>, ESSD, 2021;

Ship-going EM27/SUN



Mar. 2014: **RV**
Polarstern - Atlantic



June 2019: **RV**
Sonne - Pacific



Mar. 2021: **RV Mirai** –
Japanese coast, testing for
operational deployment in
collaboration with NIES
(National Institute for
Environmental Studies).



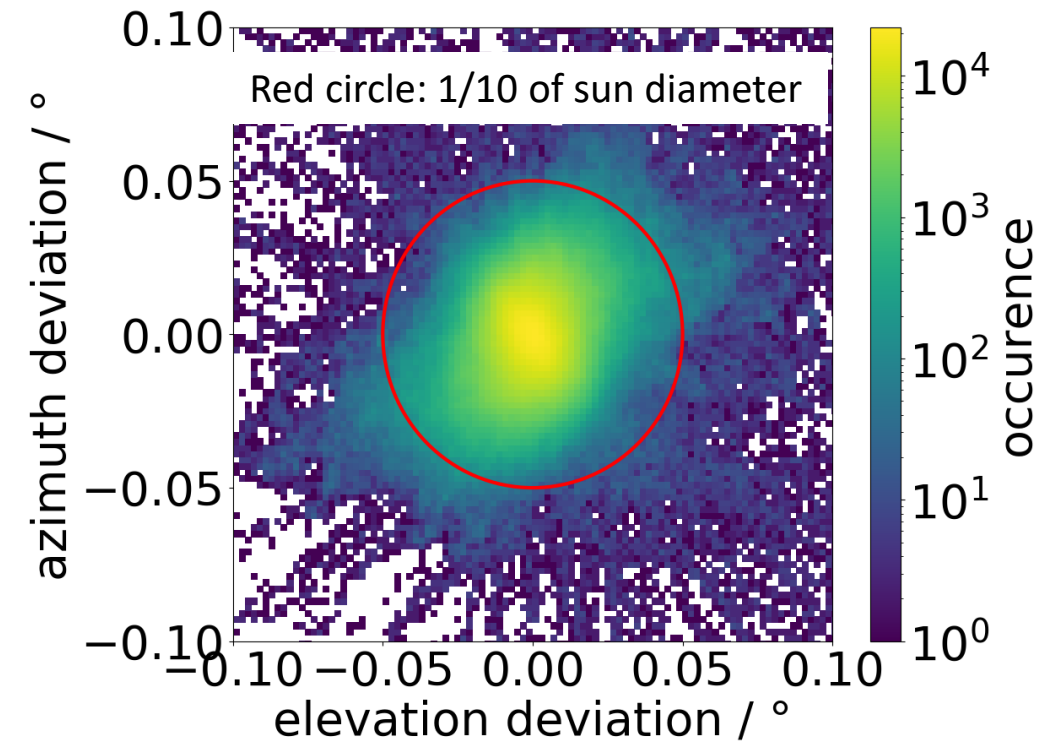
**Ship-going variant of
EM27/Sun** Fourier
Transform Spektrometer
(Bruker Optics) with
custom-built sun-tracker
und sealed housing.

Ship-going EM27/SUN

Custom-built sun-tracker enables accurate pointing to the center of the solar disk under typical platform motion.



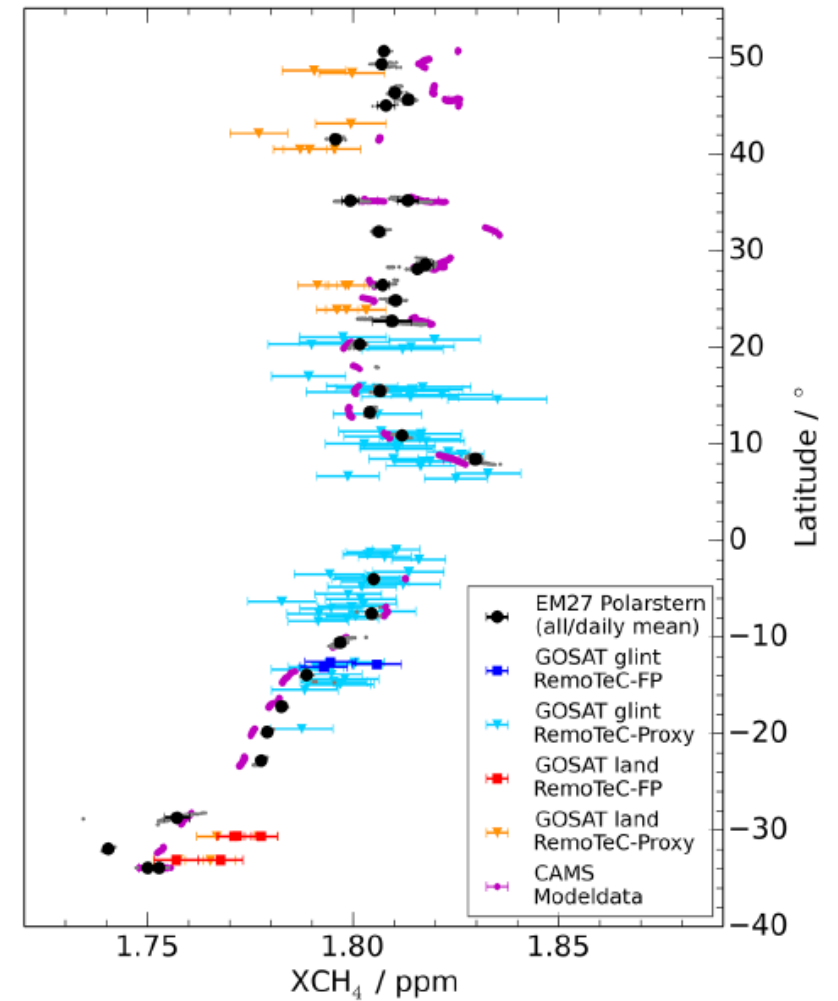
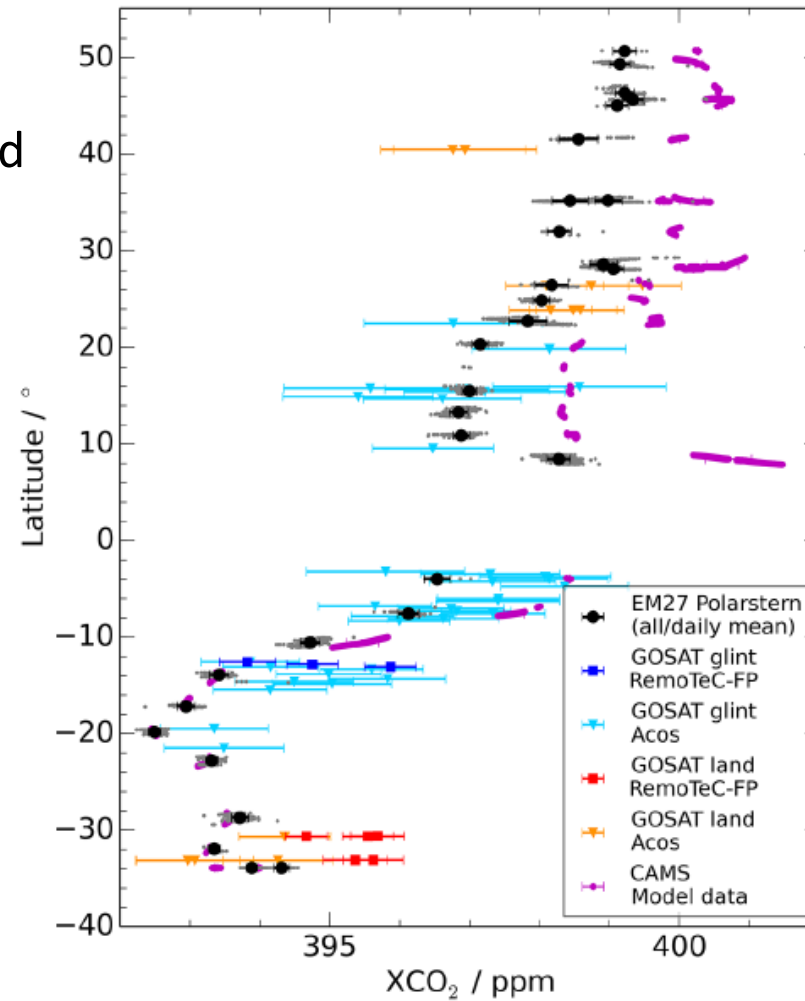
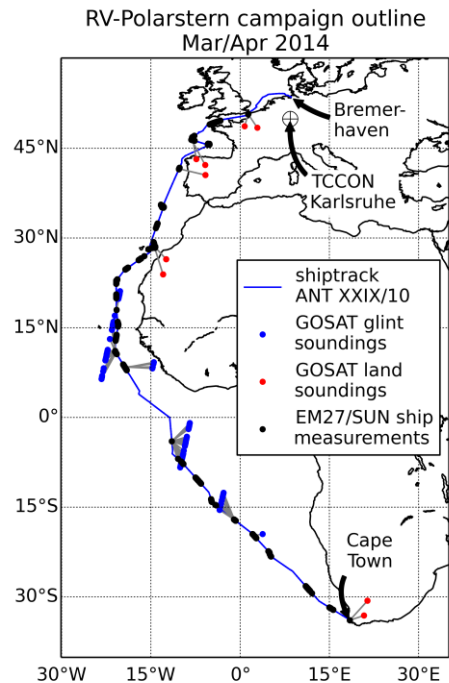
Residual pointing error
during ship cruise
(diameter solar disk 0.53°).



Ship-going EM27/SUN

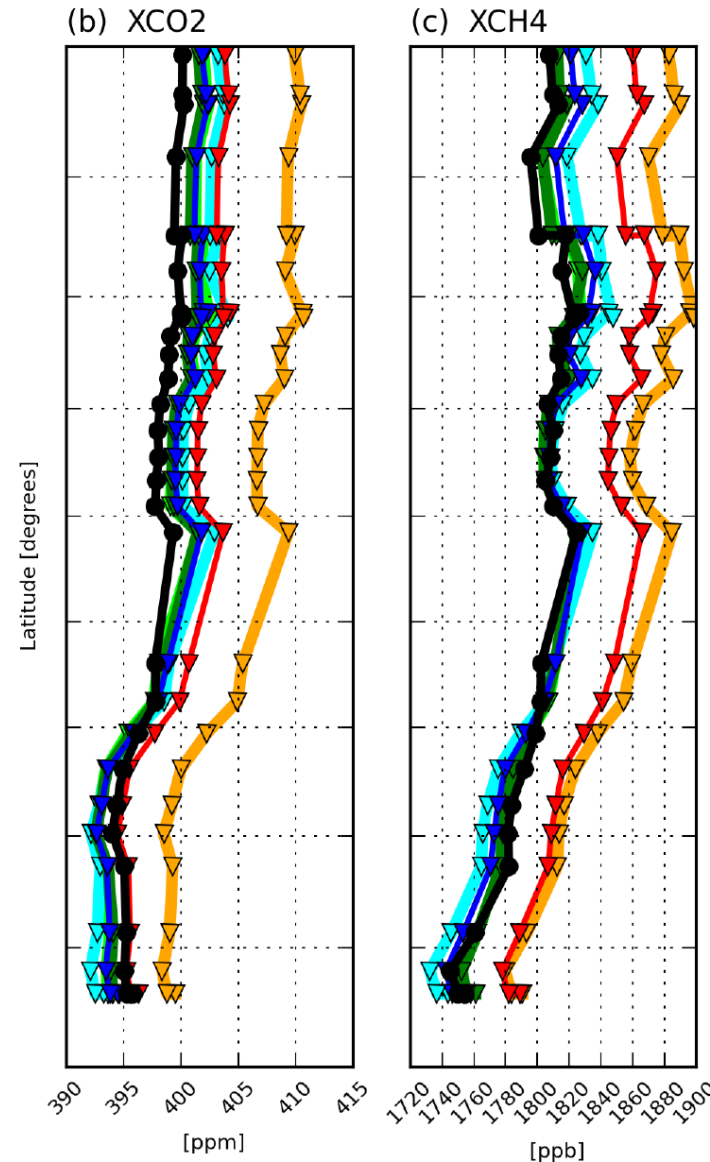
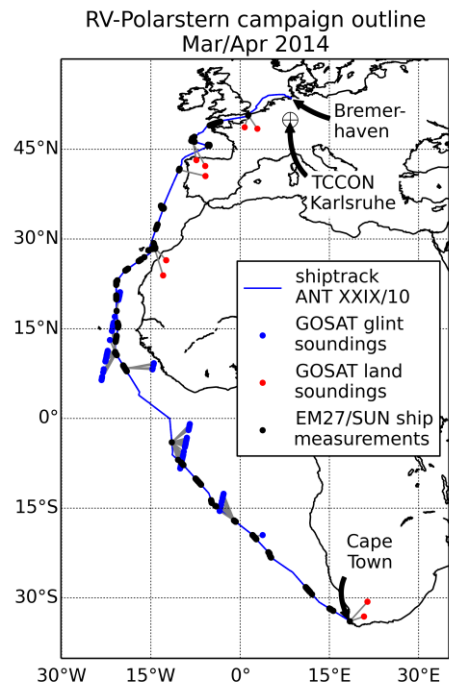


RV Polarstern 2014: South-North transect through the Atlantic Ocean for satellite and model validation of XCO_2 and XCH_4 .



Ship-going EM27/SUN

RV Polarstern 2014: South-North transect through the Atlantic Ocean for satellite and model validation of XCO_2 and XCH_4 .



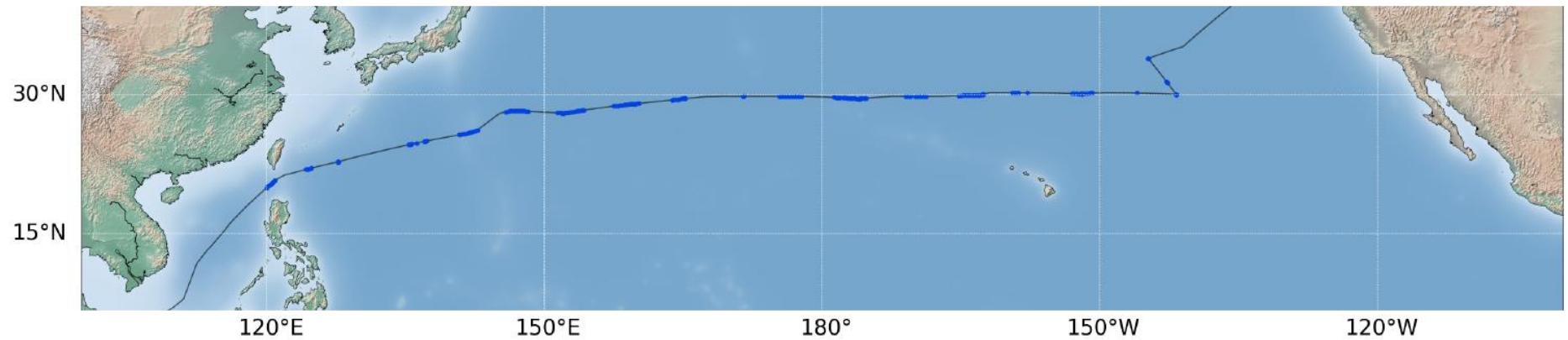
- ECMWF finds a **bias in their hemispheric greenhouse gas gradients.**
- Tuning of the „mass-fixer“** in CAMS model to fit the measured gradients.

Black: ship-borne measurements

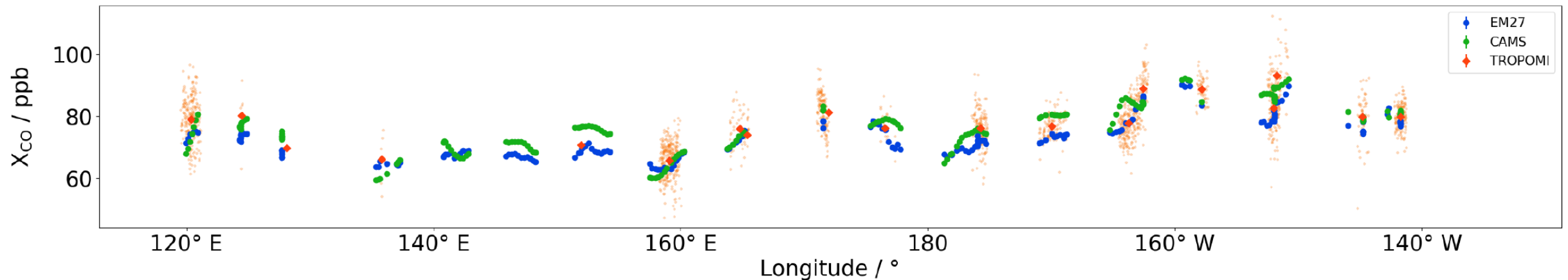
Color: various model settings

Ship-going EM27/SUN

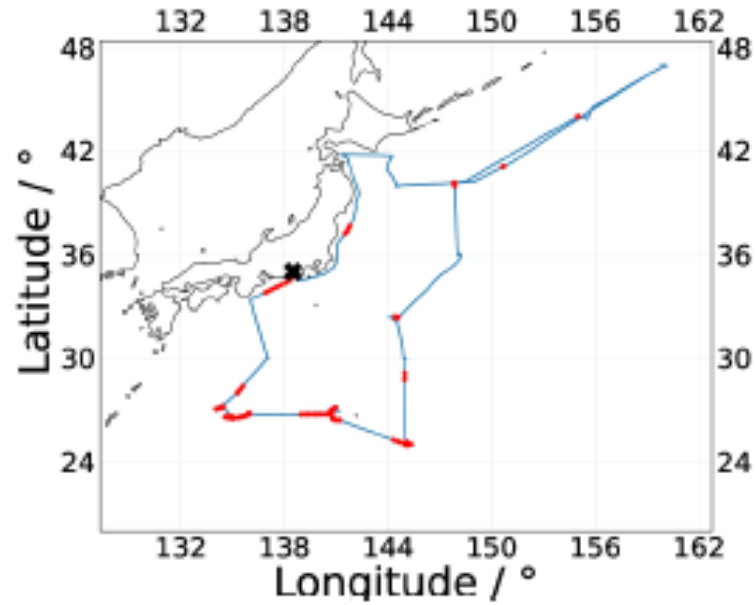
RV Sonne 2019: East-West transect through the Pacific Ocean for satellite and model validation of XCO_2 , XCH_4 , and XCO .



Ship-borne measurements and S5P/TROPOMI XCO agree to within a few ppb, likewise for CAMS.

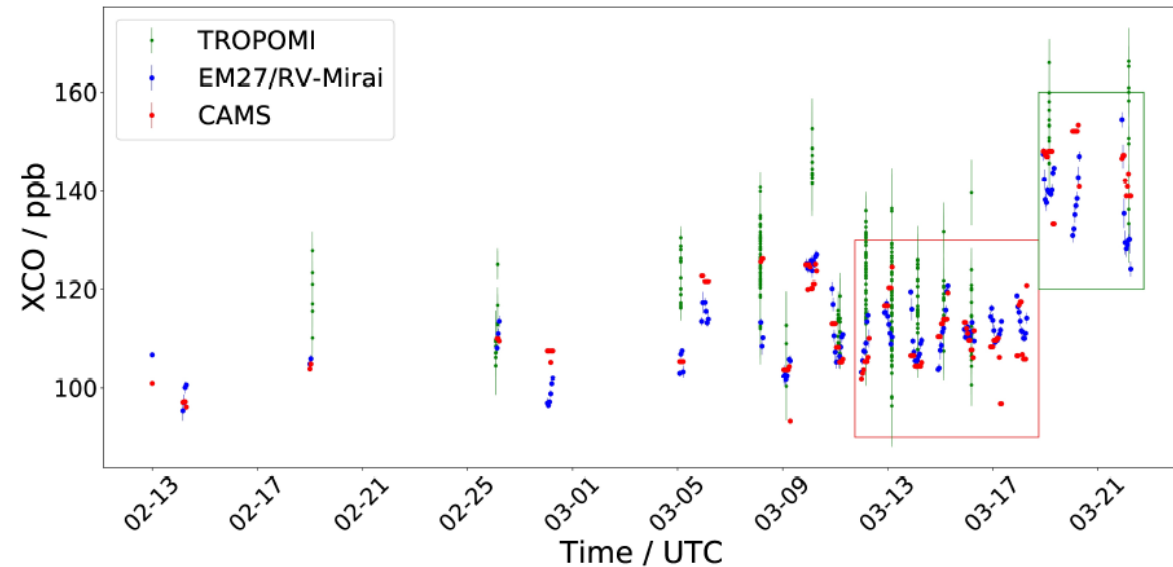
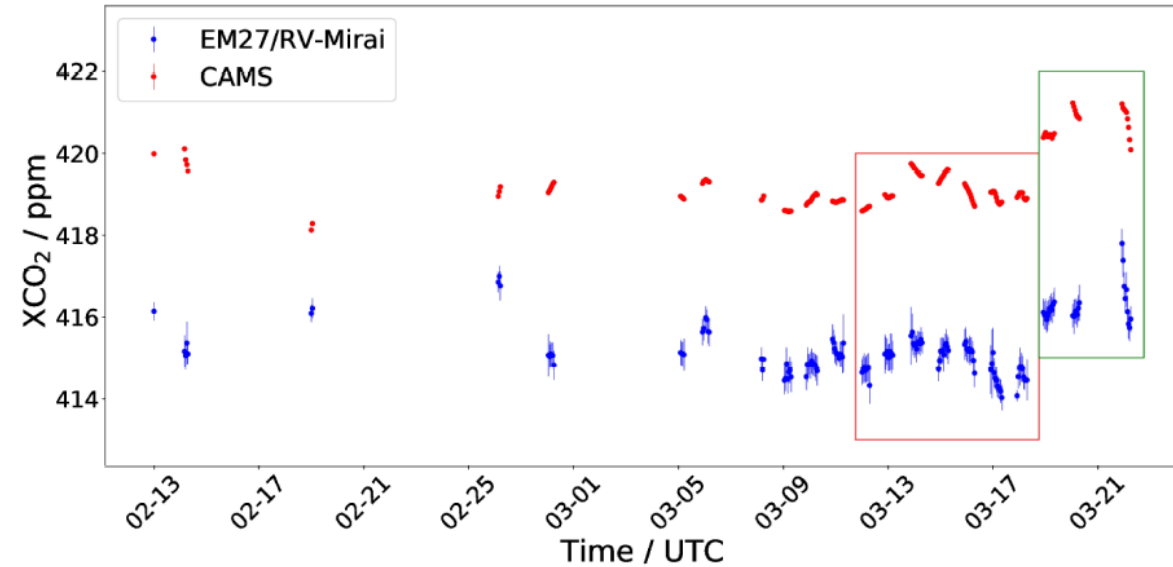


Ship-going EM27/SUN

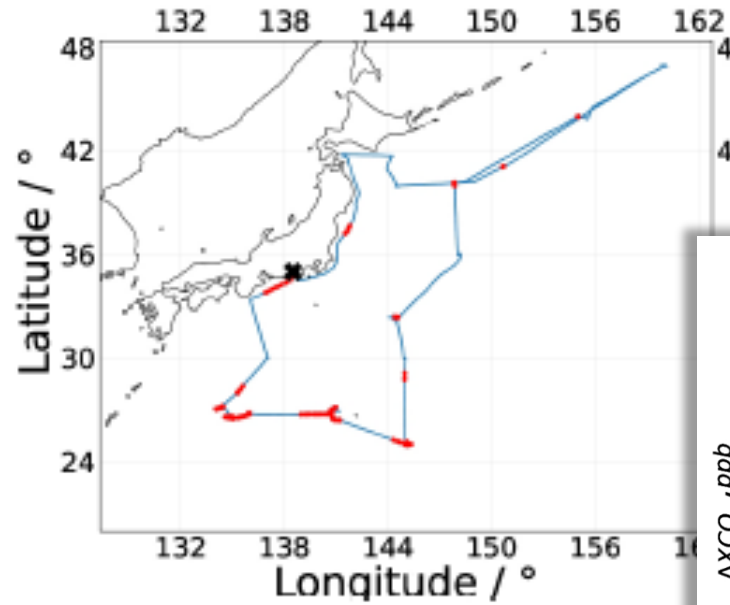


RV Mirai 2021: Pacific Ocean in the vicinity of Japan

Correlated enhancements in XCO_2 and XCO downwind of East-Asia

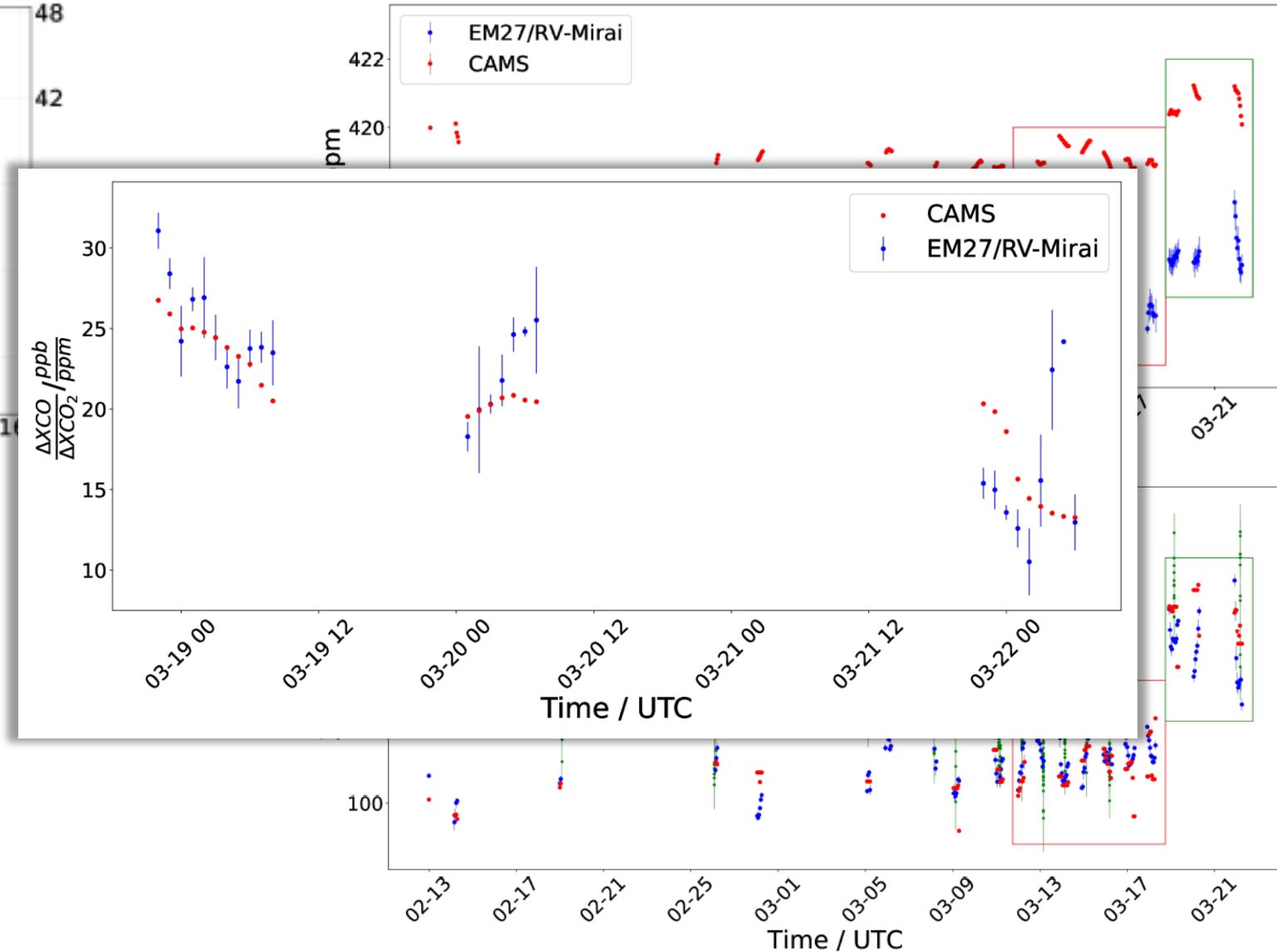


Ship-going EM27/SUN



RV Mirai 2021: Pacific Ocean in the vicinity of Japan

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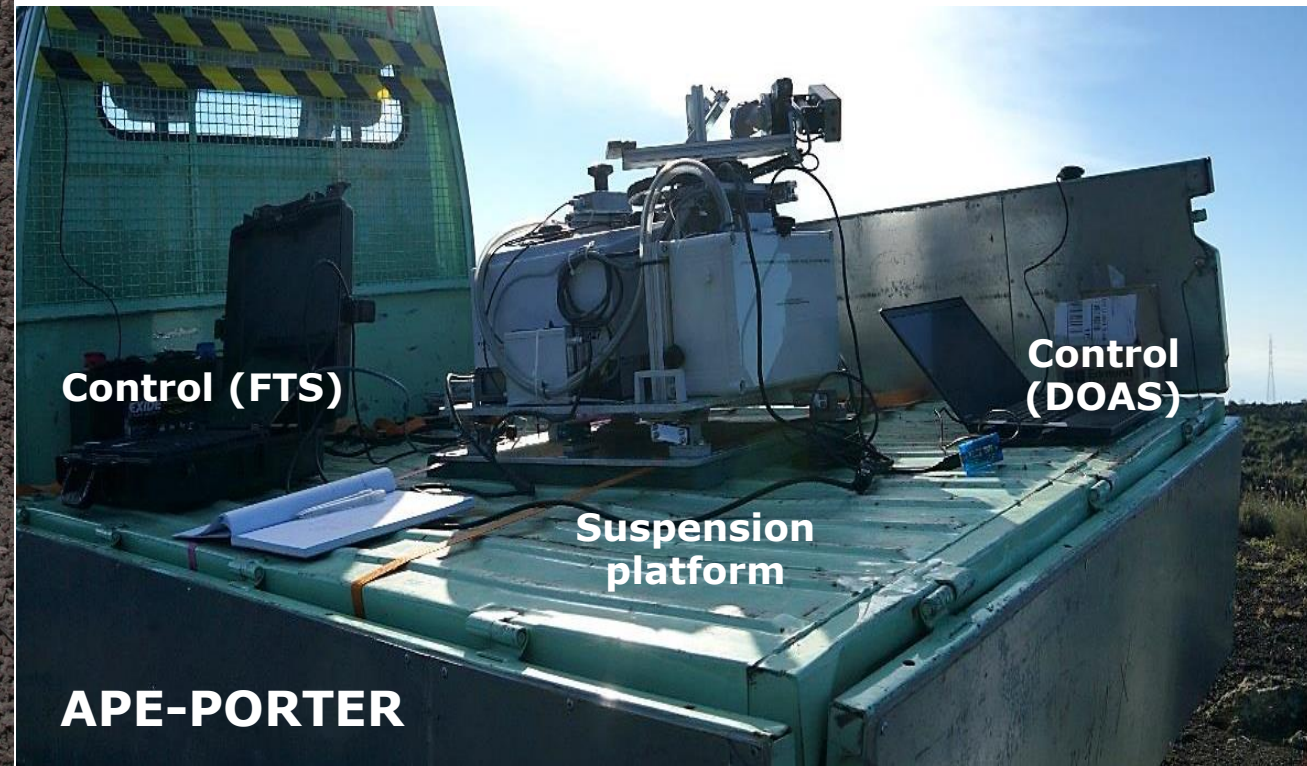


Volcano monitoring



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Volcanic CO_2/SO_2 emissions at Mt.
Etna, Sicily (Sep. 2016)



Control (FTS)

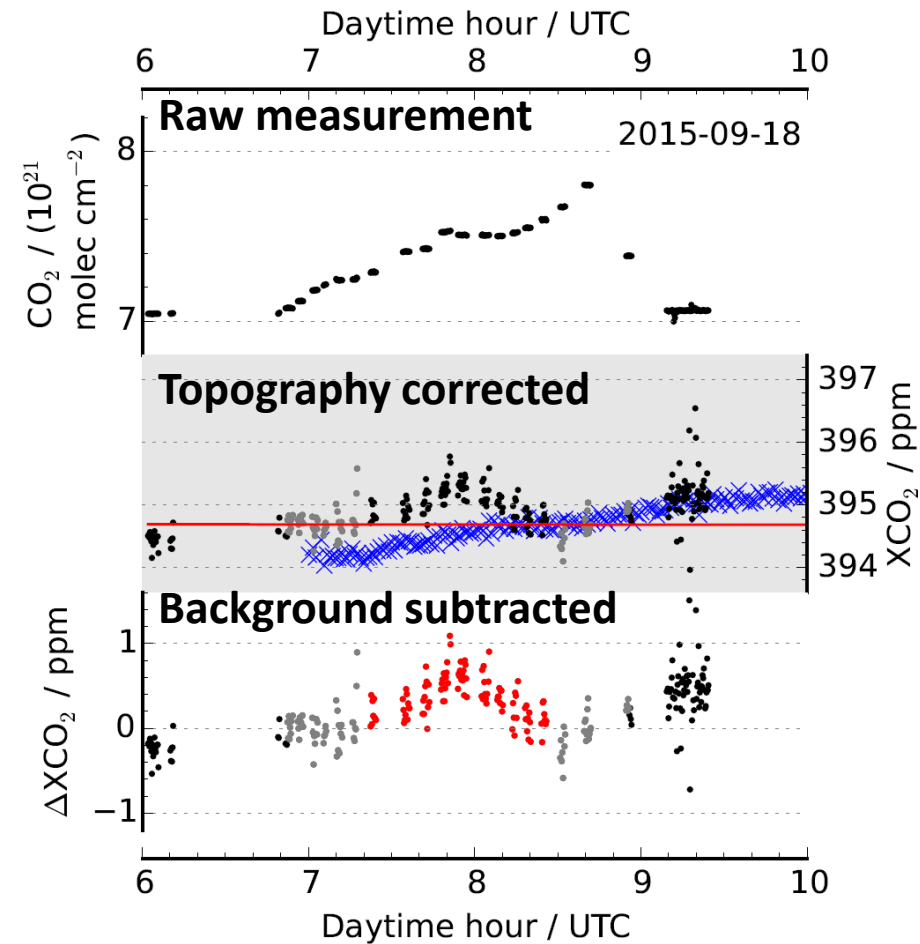
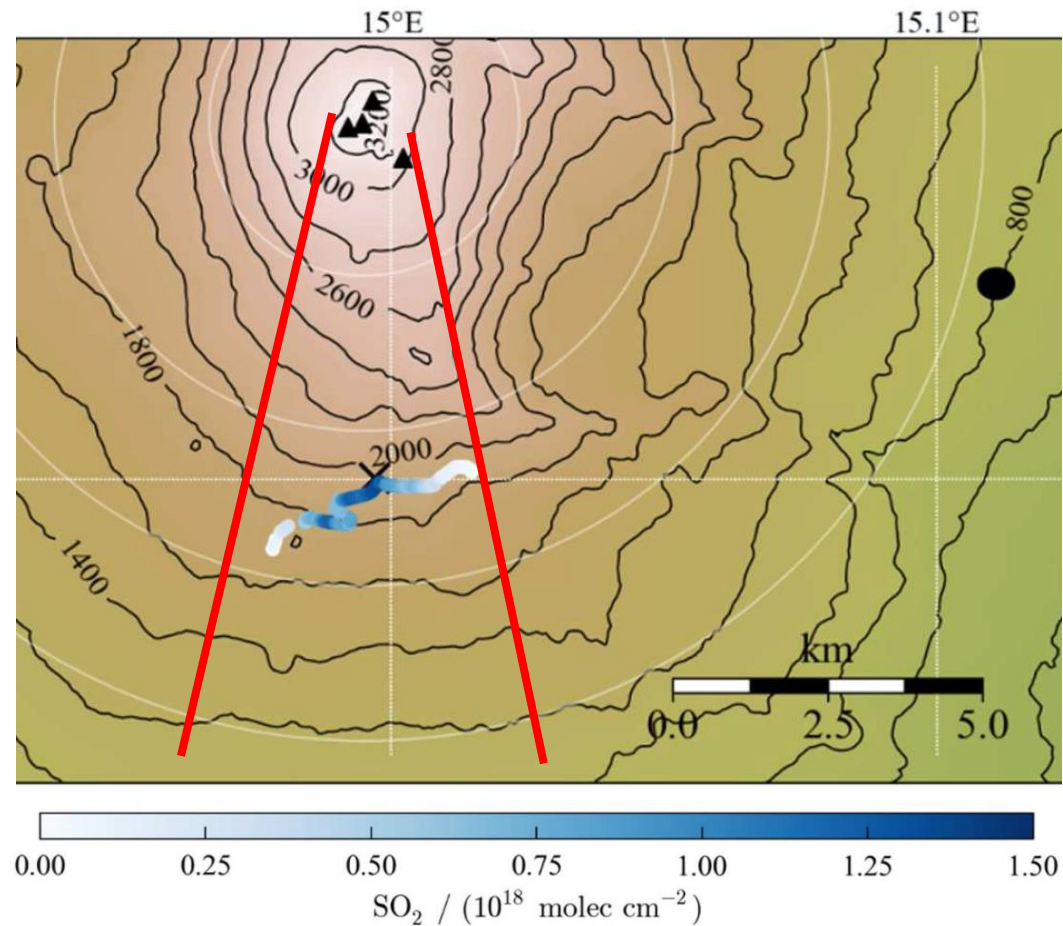
Control
(DOAS)

Suspension
platform

APE-PORTER

Volcano monitoring

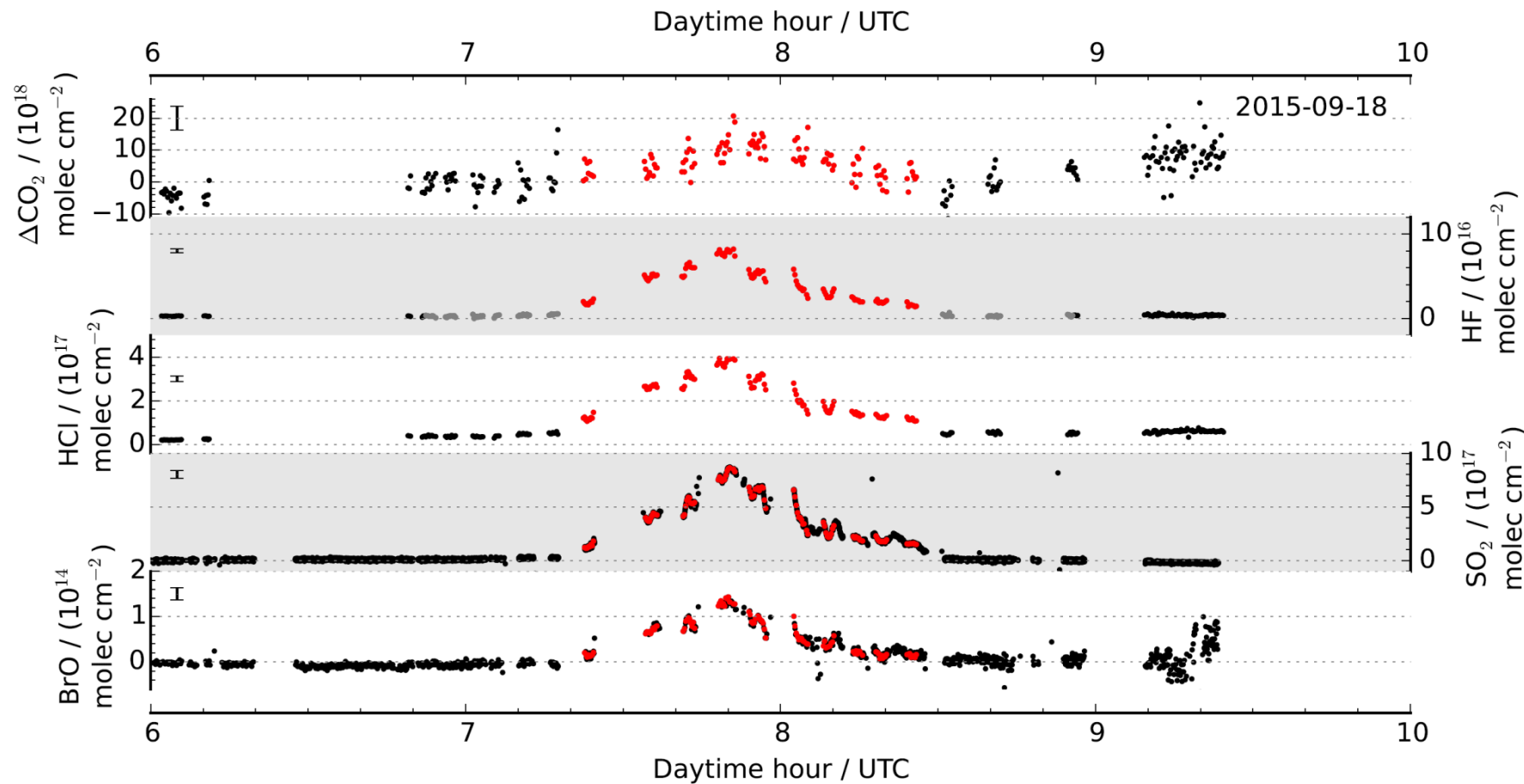
Volcanic CO₂/SO₂ emissions at Mt. Etna, Sicily (Sep. 2016)



Detection of volcanic CO₂ plume
(0.5 ppm above background) in safe distance (5-10 km) from source.

Volcano monitoring

Volcanic CO₂/SO₂ emissions at Mt. Etna, Sicily (Sep. 2016)



Co-sampling of volcanic CO₂ enhancements and SO₂, HF, HCl, BrO allows for **activity tracking and disentangling plume evolution from activity changes**.

CO₂/SO₂ ratios, for example, have been suggested promising **indicators for changes in volcanic activity**.

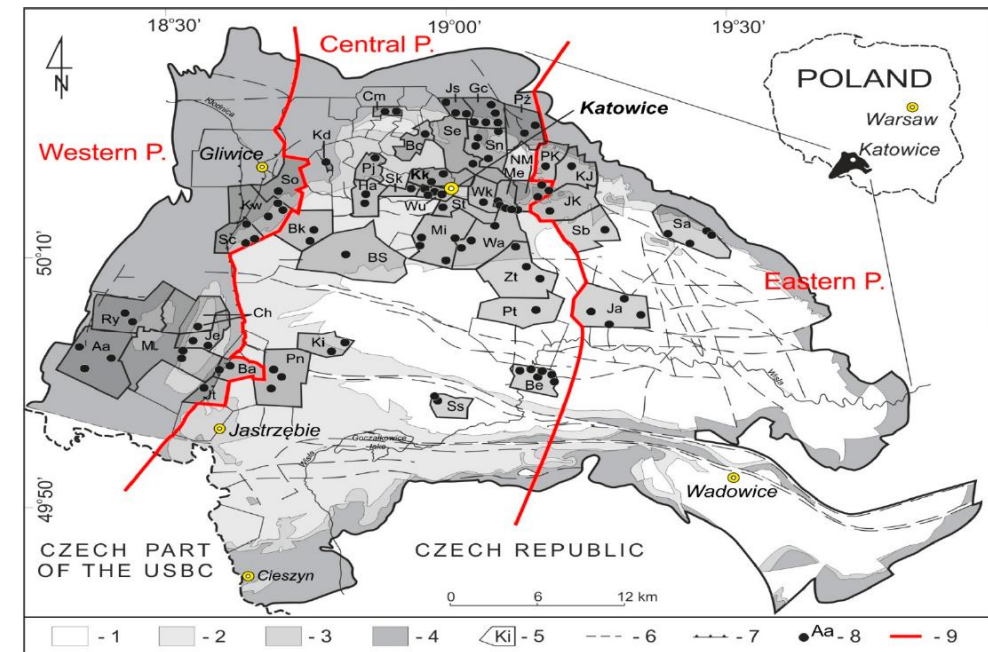


Coal mine CH₄ emissions



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CH₄ coal mine emissions in the Upper Silesian Coal Basin, Poland (May/June 2018)



[Parzentny, <https://doi.org/10.3390/min10050422>, Minerals, 2020]

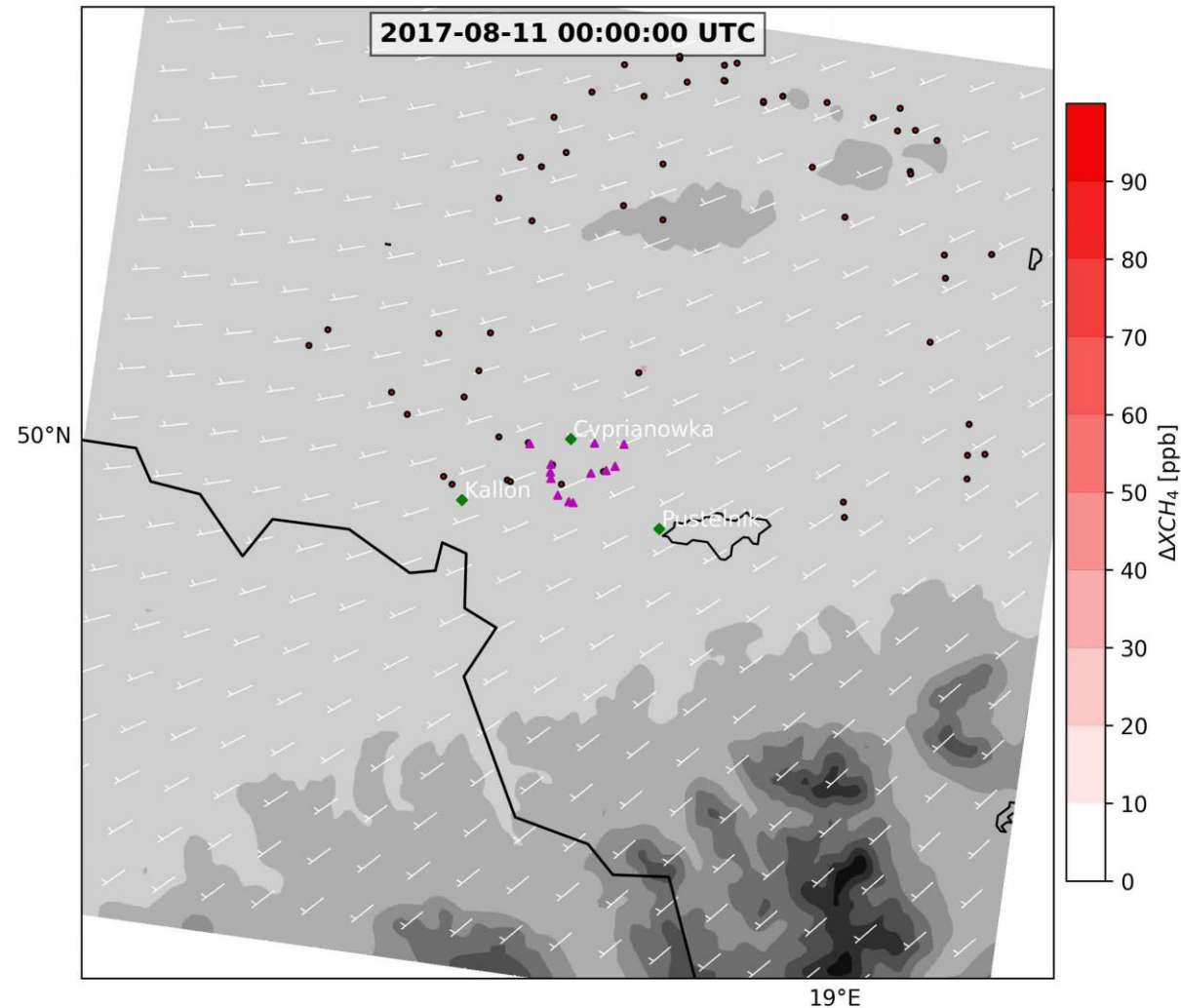
Luther et al.,
AMT, 2019



Coal mine CH₄ emissions

CH₄ coal mine emissions in
the Upper Silesian Coal Basin,
Poland (May/June 2018):

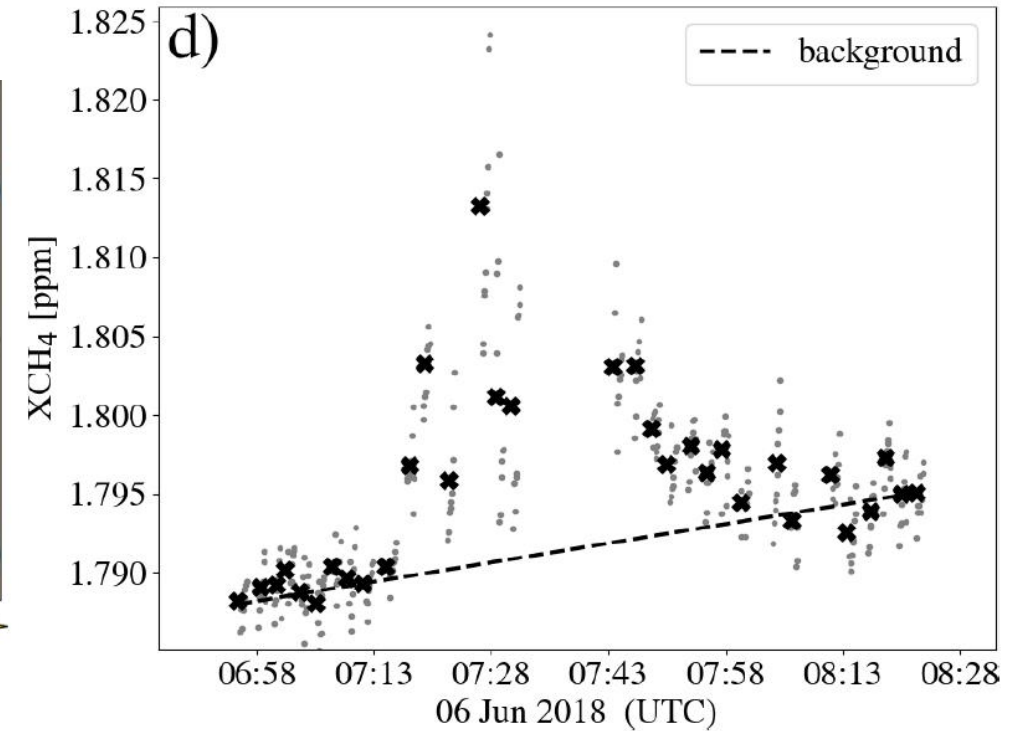
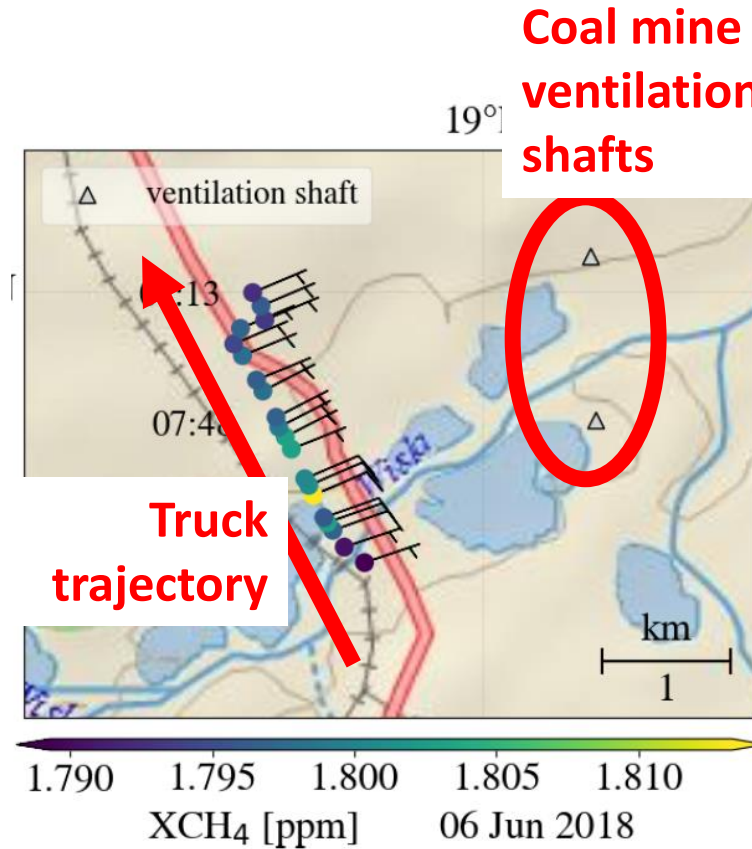
Some 50+ coal mine
ventilation shafts release CH₄
into the atmosphere,
estimated emissions of the
basin: 400-600 kt/a with
individual shafts emitting up to
20 kt/a.



Coal mine CH₄ emissions

CH₄ coal mine emissions in the Upper Silesian Coal Basin, Poland (May/June 2018):

- 1 mobile EM27/Sun
- 4 stationary EM27/Sun
- 3 Wind-Cube Doppler lidars for wind measurements.



CH₄ coal mine emissions in the Upper Silesian Coal Basin, Poland (May/June 2018):

- 1 mobile EM27/Sun
- 4 stationary EM27/Sun
- 3 Wind-Cube Doppler lidars for wind measurements.

Instantaneous emission estimates with 15-40% errors.

$$Q = \sum_i \Delta XCH_4(x_i, y_i) U_{eff}(x_i, y_i) dy_i \frac{M(CH_4)}{10^9 \times N_a}$$

ΔXCH_4 : CH₄ enhancement
 U_{eff} : effective wind speed
 dy : perpendicular path element

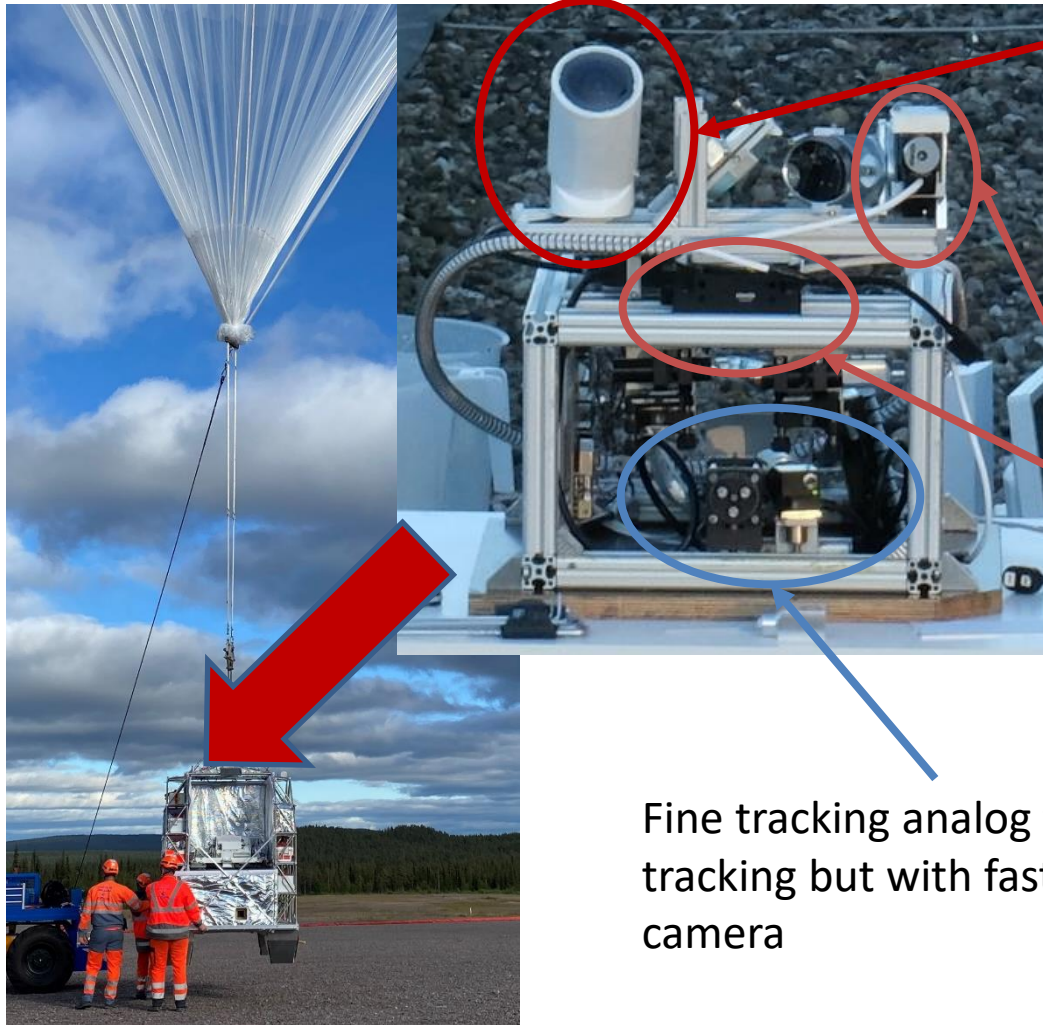
Date and time	estimated emissions [kt/a]	combined σ [kt/a] %	E-PRTR 2014 [kt/a]
24 May 7 - 8 am	6	1 19	9.63
24 May noon	10	1 15	9.63
01 June 8 - 10 am	110	38 35	-
06 June 7 - 8 am	17	3 18	24.3
06 June noon	81	13 16	~ 80

Mobile EM27/SUN



Enabling tech: custom-built, fast, self-orienting sun-tracker

Deployment on a stratospheric balloon (DOAS)



Coarse tracking
camera setup

Same rotation
stages as used
in the original
Bruker tracker

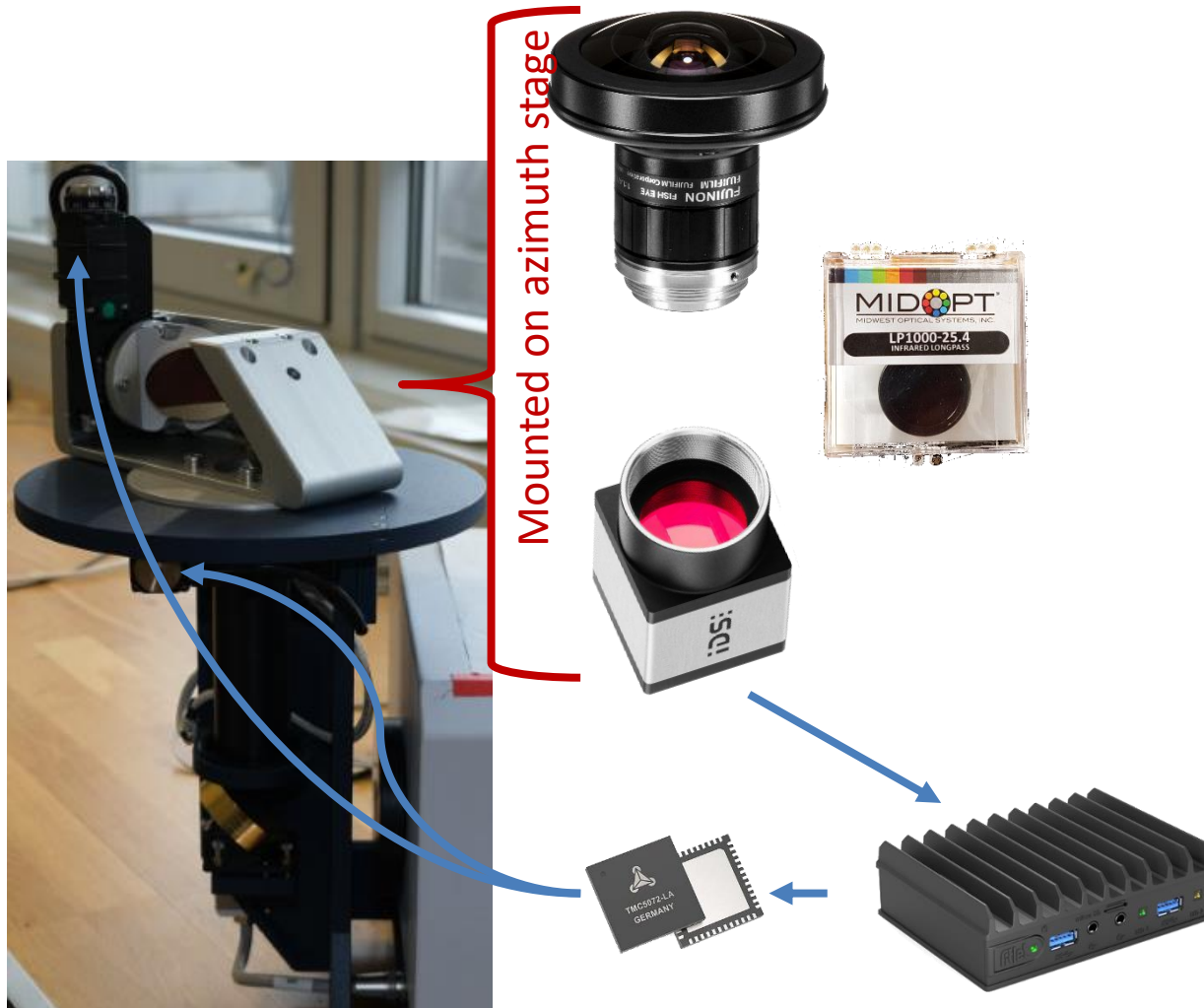
Fine tracking analog to EM27
tracking but with faster
camera

Deployment on ships (Bruker EM27 on RV Mirai)



Enabling tech: custom-built, fast, self-orienting sun-tracker

Coarse-tracking hardware



FUJINON f-theta lens (FOV 185°)	€ 500,-
Long pass (@ 1000 nm)	€ 100,-
IDS UI3280 Camera	€ 700,-
TMC 5072 stepper driver	€ 60,-
Embedded computer	€ 600,-
~ 2 k€	

For the coarse tracking, a camera with an f-theta lens is mounted directly on the azimuth stage.

A custom-made software on an embedded computer processes the images from the camera and determines the rough relative location of the sun.

A TMC motor driver operates the original Bruker rotation stage.

Enabling tech: custom-built, fast, self-orienting sun-tracker



Fine-tracking hardware

Camera adapter plate	€ 80,-
Lens with macro extension	€ 100,-
IDS UI3140 Camera	€ 700,-
	~ 1 k€

Fast fine tracking requires the change of the internal camera.

We use an IDS camera to reach frame rates up to 125 fps (without a defined area of interest or binning).

The other form factor of the camera requires an adapter plate. We will use a smaller lens for the next upgrade for better mechanical stability.

The fine-tracking software is custom-built and needs tuning (PID) for the considered application.

